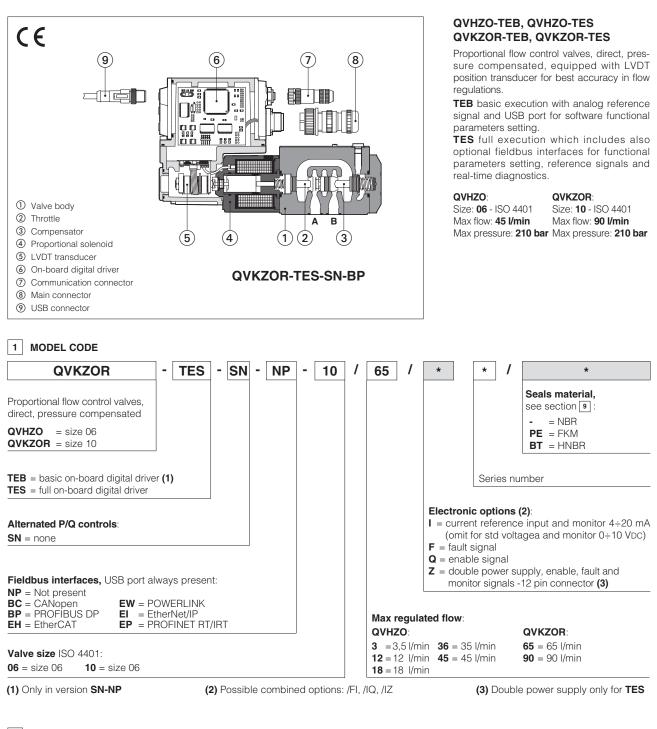
# atos

# **Digital proportional flow valves**

direct, pressure compensated, with on-board driver and LVDT transducer



# 2 HYDRAULIC SYMBOLS





The valves can be used in 2 or 3 way connection, depending to the application requirements.

In 2 way the P port must not be connected (blocked)

In **3 way** the P port has to be connected to tank or to other user lines The port T must be always not connected (blocked)

2 way connection

```
3 way connection
```

For application examples of 2 and 3 way connections, see section 11

# 3 GENERAL NOTES

Atos digital proportionals valves are CE marked according to the applicable directives (e.g. Immunity and Emission EMC Directive). Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in tech table **FS900** and in the user manuals included in the E-SW-\* programming software.

## 4 VALVE SETTINGS AND PROGRAMMING TOOLS

Valve's functional parameters and configurations, can be easily set and optimized using Atos E-SW programming software connected via USB port to the digital driver (see table **FS900**). For fieldbus versions, the software permits valve's parameterization through USB port also if the driver is connected to the central machine unit via fieldbus.

 The software is available in different versions according to the driver's options (see table GS500):

 E-SW-BASIC
 support:
 NP (USB)
 PS (Serial)
 IR (Infrared)

 E-SW-FIELDBUS
 support:
 BC (CANopen)
 BP (PROFIBUS DP)
 EH (EtherCAT)

 E-SW-\*/PQ
 support:
 valves with SP, SF, SL alternated control (e.g. E-SW-BASIC/PQ)

WARNING: drivers USB port is not isolated! For E-C-SB-USB/M12 cable, the use of isolator adapter is highly recommended for PC protection

WARNING: see tech table GS500 for the list of countries where the Bluetooth adapter has been approved

#### 5 FIELDBUS - only for TES, see tech. table GS510

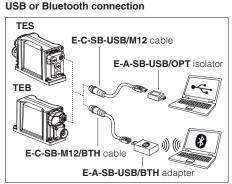
Fieldbus allows valve direct communication with machine control unit for digital reference, valve diagnostics and settings. These execution allow to operate the valves through fieldbus or analog signals available on the main connector.

#### 6 GENERAL CHARACTERISTICS

Assembly position	Any position					
Subplate surface finishing to ISO 4401	Acceptable roughness index: Ra ≤0,8, recommended Ra 0,4 – Flatness ratio 0,01/100					
MTTFd valves according to EN ISO 13849	150 years, see technical table P007					
Ambient temperature range	<b>Standard</b> = $-20^{\circ}C \div +60^{\circ}C$	<b>/PE</b> option = $-20^{\circ}C \div +60^{\circ}C$	<b>/BT</b> option = $-40^{\circ}C \div +60^{\circ}C$			
Storage temperature range	Standard = -20°C ÷ +70°C	<b>/PE</b> option = -20°C ÷ +70°C	<b>/BT</b> option = $-40^{\circ}C \div +70^{\circ}C$			
Surface protection	Zinc coating with black passivation, galvanic treatment (driver housing)					
Corrosion resistance	Salt spray test (EN ISO 9227) > 200 h					
Compliance	CE according to EMC directive 2014/30/EU (Immunity: EN 61000-6-2; Emission: EN 61000-6-3) RoHS Directive 2011/65/EU as last update by 2015/65/EU REACH Regulation (EC) n°1907/2006					

#### 7 HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

Valve model		QVHZO					QVKZOR	
Max regulated	flow [I/min]	3,5	12	18	35	45	65	90
Min regulated	flow [cm³/min]	15	20	30	50	60	85	100
Regulating ∆p [bar]		4 - 6 10 - 12			15	6 - 8	10 - 12	
Max flow on p	Nax flow on port A [l/min]		50					100
Max pressure	[bar]	210					210	
Response time 0÷100% step signal [ms]		25					3	35
Hysteresis	[% of the regulated max flow]	0,5					C	,5
Linearity [% of the regulated max flow]		0,5					0,5	
Repeatability	[% of the regulated max flow]	0,1					C	,1
Thermal drift		zero point displacement < 1% at $\Delta T = 40^{\circ}C$						



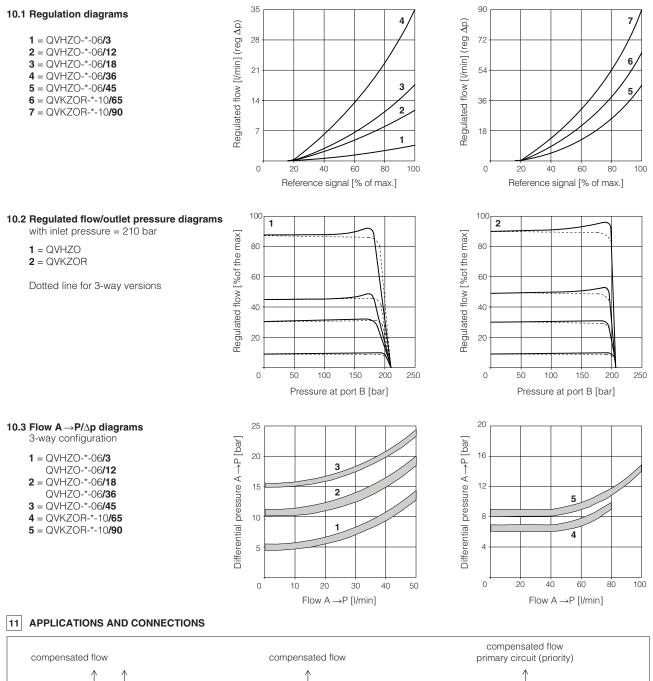
# 8 ELECTRICAL CHARACTERISTICS

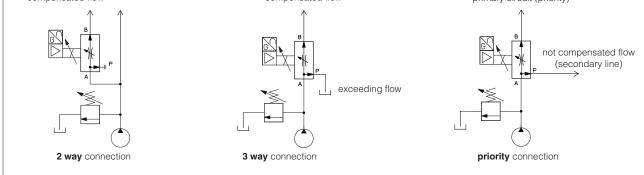
Power supplies	Nominal Rectified and filtered	: +24 VDC : VRMS = 20 ÷ 32 VMAX	(ripple max 10 % VPP)				
Max power consumption	50 W						
Max. solenoid current	<b>QVHZO</b> = 2,6 A	QVKZOR = 3 A					
Coil resistance R at 20°C	<b>QVHZO</b> = $3 \div 3,3 \Omega$	QVKZOR = 3,8 ÷	÷ 4,1 Ω				
Analog input signals	Voltage: range ±10 V Current: range ±20 m	( /	Input impedance Input impedance				
Monitor outputs		Dutput range:         voltage         ±10 Vbc @ max 5 mA           current         ±20 mA @ max 500 Ω load resistance					
Enable input	Range: 0 ÷ 5 VDC (OFF	state), 9 ÷ 24 VDC (ON s	state), 5 ÷ 9 VDC (not acc	epted); Input impedance: $Ri > 10 k\Omega$			
Fault output		Output range: 0 ÷ 24 VDC (ON state > [power supply - 2 V]; OFF state < 1 V) @ max 50 mA; external negative voltage not allowed (e.g. due to inductive loads)					
Alarms	Solenoid not connected/short circuit, cable break with current reference signal, over/under temperature, valve spool transducer malfunctions, alarms history storage function						
Insulation class		H (180°) Due to the occuring surface temperatures of the solenoid coils, the European standards ISO 13732-1 and EN982 must be taken into account					
Protection degree to DIN EN60529	IP66 / IP67 with mating	g connectors					
Duty factor	Continuous rating (ED=	=100%)					
Tropicalization	Tropical coating on ele	ectronics PCB					
Additional characteristics			upply; 3 leds for diagnos nst reverse polarity of po	stic; spool position control by P.I.D. ower supply			
Communication interface	USB	CANopen	PROFIBUS DP	EtherCAT, POWERLINK, EtherNet/IP, PROFINET IO RT / IRT			
	Atos ASCII coding	EN50325-4 + DS408	EN50170-2/IEC61158	EC 61158			
Communication physical layer	not insulated USB 2.0 + USB OTG	optical insulated CAN ISO11898	optical insulated RS485	Fast Ethernet, insulated 100 Base TX			
Recommended wiring cable	LiYCY shielded cables	s, see section 17					

Note: a maximum time of 800 ms (depending on communication type) have be considered between the driver energizing with the 24 Vbc power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero.

9	SEALS AND HYDRAULIC FLUIDS	- for other fluids not included in below table, consult our technical office
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		NBR seals (standard) = $-20^{\circ}$ C ÷ $+60^{\circ}$ C, with HFC hydraulic fluids = $-20^{\circ}$ C ÷ $+50^{\circ}$ C					
Seals, recommended fluid temperature		FKM seals (/PE option) = $-20^{\circ}C \div +80^{\circ}C$					
		HNBR seals (/BT option) = $-40^{\circ}C \div +60^{\circ}C$ , with HFC hydraulic fluids = $-40^{\circ}C \div +50^{\circ}C$					
Recommended viscosity		20÷100 mm²/s - max allowed range 15 ÷ 380 mm²/s					
Max fluid	normal operation	ISO4406 class 18/16/13 NAS1	638 class 7	see also filter section at			
contamination level	longer life	ISO4406 class 16/14/11 NAS1	638 class 5	www.atos.com or KTF catalog			
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard			
Mineral oils		NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524			
Flame resistant without water		FKM HFDU, HFDR		ISO 12922			
Flame resistant with water		NBR, HNBR	HFC	100 12922			





#### 2 way connection

The 2 way connection is normally used to control the flow in one part of the hydraulic circuit or to regulate the speed of a specific actuator. The metered flow in the controlled line is kept constant, independently to the load variations

If the valve is directly installed on the pump main line, the exceeding flow is returned to tank though the pressure relief valve.

#### 3 way connection

The 3 way connection is normally used when the valve directly controls the pump flow (main line)

The metered flow in the controlled line is kept constant, independently to the load variations

The exceeding flow (not metered by the valve) it is returned to tank trough the valve P port = T line (3rd way)

#### **Priority connection**

The priority connection guarantees the pressure compensated flow supply to the primary circuit.

The exceeding flow (not required by the primary circuit) is bypassed through the valve P port, to secondary circuit operating at lower pressure and not requiring compensated flow regulations.

# 12 ELECTRONICS OPTIONS

- **F** = This option permits to monitor the eventual fault condition of the driver, as for example the solenoid short circuit/not connected, reference signal cable broken for option /l, spool position transducer broken, etc. see 14.7 for signal specifications.
- This option provides 4 ÷ 20 mA current reference and monitor signals, instead of the standard 0 ÷ 10 VDC.
   Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ±20 mA.
   It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.
- Q = This option permits to inhibit the valve function without removing the power supply to the driver. Upon disable command the current to the solenoid is zeroed and the valve's spool moves to rest position.
   The option /Q is suggested for all cases where the valve has to be frequently inhibited during the machine cycle see 14.5 for signal specifications.

Z = This option provides, on the 12 pin main connector, the following additional features:
 Fault output signal - see above option /F
 Enable input signal - see above option /Q
 Repeat enable output signal - only for TEB (see 14.6)
 Power supply for driver's logics and communication - only for TES (see 14.2)

# 13 POSSIBLE COMBINED OPTIONS

/FI, /IQ, /IZ

#### 14 POWER SUPPLY AND SIGNALS SPECIFICATIONS

Generic electrical output signals of the valve (e.g. fault or monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, ISO 4413).

## 14.1 Power supply (V+ and V0)

The power supply must be appropriately stabilized or rectified and filtered: apply at least a 10000  $\mu$ F/40 V capacitance to single phase rectifiers or a 4700  $\mu$ F/40 V capacitance to three phase rectifiers. In case of separate power supply see 14.2.

A safety fuse is required in series to each power supply: 2,5 A time lag fuse.

# 14.2 Power supply for driver's logic and communication (VL+ and VL0) - only for /Z

The power supply for driver's logic and communication must be appropriately stabilized or rectified and filtered: apply at least a 10000  $\mu$ F/40 V capacitance to single phase rectifiers or a 4700  $\mu$ F/40 V capacitance to three phase rectifiers.

The separate power supply for driver's logic on pin 9 and 10, allow to remove solenoid power supply from pin 1 and 2 maintaining active the diagnostics, USB and fieldbus communications.

A safety fuse is required in series to each driver's logic and communication power supply: 500 mA fast fuse.

#### 14.3 Flow reference input signal (Q\_INPUT+)

The driver controls in closed loop the valve spool position proportionally to the external reference input signal. Reference input signal is factory preset according to selected valve code, defaults are  $0 \div 10$  Vpc for standard and  $4 \div 20$  mA for /l option.

Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of  $\pm 10$  VDC or  $\pm 20$  mA. Drivers with fieldbus interface can be software set to receive reference signal directly from the machine control unit (fieldbus reference). Analog reference input signal can be used as on-off commands with input range  $0 \div 24$ VDC.

#### 14.4 Flow monitor output signal (Q\_MONITOR) - not for /F

The driver generates an analog output signal proportional to the actual spool position of the valve; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, fieldbus reference, pilot spool position). Monitor output signal is factory preset according to selected valve code, defaults are  $\pm 10$  VDC for standard and  $4 \div 20$  mA for /l option. Output signal can be reconfigured via software selecting between voltage and current, within a maximum range of  $\pm 10$  VDC or  $\pm 20$  mA.

#### 14.5 Enable input signal (ENABLE) - not for standard and /F

To enable the driver, supply a 24 VDC on pin 3 (pin C): Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to active the communication and the other driver functions when the valve must be disabled for safety reasons. This condition **does not comply** with norms IEC 61508 and ISO 13849. Enable input signal can be used as generic digital input by software selection.

#### 14.6 Repeat enable output signal (R\_ENABLE) - only for TEB with /Z option

Repeat enable is used as output repeater signal of enable input signal (see 14.5).

#### 14.7 Fault output signal (FAULT) - not for standard and /Q

Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for 4 ÷ 20 mA input, spool position transducer cable broken, etc.). Fault presence corresponds to 0 VDC, normal working corresponds to 24 VDC. Fault status is not affected by the Enable input signal. Fault output signal can be used as digital output by software selection.

# 15 ELECTRONIC CONNECTIONS AND LEDS

PIN	Standard /Q /F		/F	TECHNICAL SPECIFICATIONS	NOTES
Α	V+			Power supply 24 Vbc	Input - power supply
В	V0			Power supply 0 VDc	Gnd - power supply
С	AGND	AGND AGND		Analog ground	Gnd - analog signal
	ENABLE			Enable (24 VDC) or disable (0 VDC) the valve, referred to V0	Input - on/off signal
D				Flow reference input signal: ±10 Vpc / ±20 mA maximum range	Input - analog signal
	Q_INPUT+	Q_INPUT+		Defaults are 0 ÷ 10 Vpc for standard and 4 ÷ 20 mA for /I option	Software selectable
E	INPUT-			Negative reference input signal for Q_INPUT+	Input - analog signal
	Q_MONITO	R referred to:		Flow monitor output signal: ±10 Vpc / ±20 mA maximum range	Output - analog signal
F	AGND V0			Defaults are 0 ÷ 10 Vpc for standard and 4 ÷ 20 mA for /I option	Software selectable
	FAULT		FAULT	Fault (0 Vbc) or normal working (24 Vbc)	Output - on/off signal
G	EARTH			Internally connected to the driver housing	

# 15.1 Main connector signals - 7 pin - standard, /F and /Q options $\widehat{\mbox{A1}}$

# 15.2 Main connector signal - 12 pin - /Z option (A2)

PIN	TEB-SN /Z	TES-SN /Z	TECHNICAL SPECIFICATIONS	NOTES
	V+		Power supply 24 Vbc	Input - power supply
1	V0		Power supply 0 VDc	Gnd - power supply
2	ENABLE ref	IABLE referred to: Enable (24 Vbc) or disable (0 Vbc) the valve		Input - on/off signal
3	VO	VL0		input onjoir signal
4			Flow reference input signal: ±10 Vpc / ±20 mA maximum range	Input - analog signal
4	Q_INPUT+		Defaults are 0 ÷ 10 Vpc for standard and 4 ÷ 20 mA for /I option	Software selectable
5	INPUT-		Negative reference input signal for Q_INPUT+	Input - analog signal
6	Q_MONITOR	referred to:	Flow monitor output signal: ±10 Vpc / ±20 mA maximum range	Input - analog signal
0	AGND	VLO	Defaults are 0 ÷ 10 Vpc for standard and 4 ÷ 20 mA for /I option	Software selectable
7	AGND		Analog ground	Output - analog signal
'		NC	Do not connect	Gnd - analog signal
8	R_ENABLE		Repeat enable, output repeter signal of enable input, referred to V0	Output - on/off signal
0		NC	Do not connect	
9	NC		Do not connect	
9		VL+	Power supply 24 VDc for driver's logic and communication	Input - power supply
10	NC		Do not connect	
10		VL0	Power supply 0 VDc for driver's logic and communication	Gnd - power supply
11	FAULT refer	red to:	Fault (0 Vpc) or normal working (24 Vpc)	Output - on/off signal
PE	VO	VL0		
	EARTH		Internally connected to the driver housing	

Note: do not disconnect VL0 before VL+ when the driver is connected to PC USB port

## 15.3 Communications connectors (B) - (C)

B USB connector - M12 - 5 pin always present					
PIN	SIGNAL	<b>TECHNICAL SPECIFICATION</b> (1)			
1	+5V_USB	Power supply			
2	ID	Identification			
3	GND_USB	Signal zero data line			
4	D-	Data line -			
5	D+	Data line +			

C1 (	C1 C2 BP fieldbus execution, connector - M12 - 5 pin			
PIN	PIN SIGNAL TECHNICAL SPECIFICATION (1)			
1	+5V	Termination supply signal		
2	LINE-A	Bus line (high)		
3	DGND	Data line and termination signal zero		
4	LINE-B	Bus line (low)		
5	SHIELD			

(1) shield connection on connector's housing is recommended

 Image: Signal system
 TECHNICAL SPECIFICATION (1)

 1
 CAN\_SHLD
 Shield

 2
 not used
 (i) - (i) pass-through connection (2)

 3
 CAN\_GND
 Signal zero data line

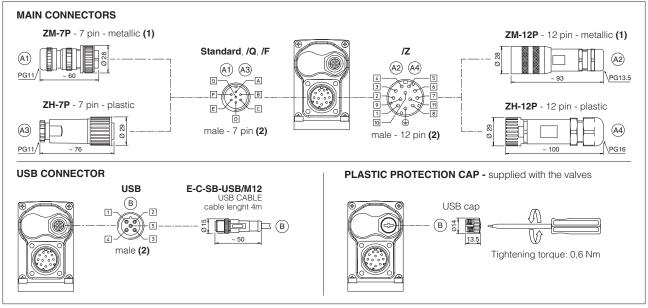
 4
 CAN\_H
 Bus line (high)

 5
 CAN\_L
 Bus line (low)

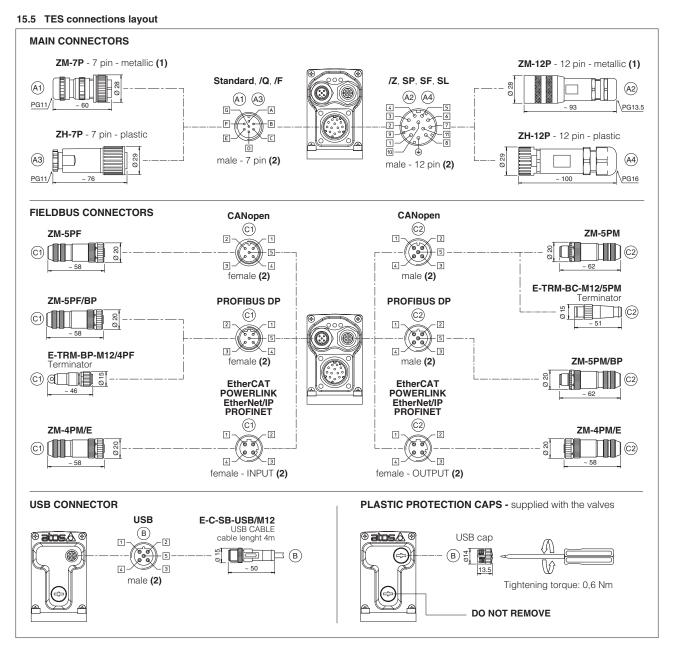
©1 (	C1 C2 EH, EW, EI, EP fieldbus execution, connector - M12 - 4 pin				
PIN	IN SIGNAL TECHNICAL SPECIFICATION (1)				
1	TX+	Transmitter			
2	RX+	Receiver			
3	TX-	Transmitter			
4	RX-	Receiver			
	SHIELD				

(2) Pin 2 can be fed with external +5V supply of CAN interface

#### 15.4 TEB connections layout



(1) Use of metallic connectors is strongly recommended in order to fulfill EMC requirements (2) Pin layout always referred to driver's view



#### (1) Use of metallic connectors is strongly recommended in order to fulfill EMC requirements

(2) Pin layout always referred to driver's view

#### 15.6 Diagnostic LEDs - only for TES

Three leds show driver operative conditions for immediate basic diagnostics. Please refer to the driver user manual for detailed information.

FIELDBU	S NP Not Present	BC CANopen	BP PROFIBUS DP	EH EtherCAT	EW POWERLINK	El EtherNet/IP	EP PROFINET	L1 L2 L3
L1		VALVE STATU	6		LIN	K/ACT		
L2	N	ETWORK STAT	US		NETWOF	IK STATUS		
L3	SC	DLENOID STAT	US		LIN	K/ACT		00

# 16 IN / OUT FIELDBUS COMMUNICATION CONNECTORS

Two fieldbus communication connectors are always available for digital drivers executions BC, BP, EH, EW, EI, EP. This features allows considerable technical advantages in terms of installation simplicity, wirings reduction and also avoid the usage expensive T-connectors.

also avoid the usage expensive T-connectors. For BC and BP executions the fieldbus connectors have an internal pass-through connection and can be used like end point of the fieldbus network, using an external terminator (see tech table **GS500**).

For EH, EW, EI and EP executions the external terminators are not required: each connector is internally terminated.

# 17 CONNECTORS CHARACTERISTICS - to be ordered separately

#### 17.1 Main connectors - 7 pin

CONNECTOR TYPE	POWER SUPPLY	POWER SUPPLY
CODE	(A1) ZM-7P	A3 ZH-7P
Туре	7pin female straight circular	7pin female straight circular
Standard	According to MIL-C-5015	According to MIL-C-5015
Material	Metallic	Plastic reinforced with fiber glass
Cable gland	PG11	PG11
Recommended cable	LiYCY 7 x 0,75 mm <sup>2</sup> max 20 m (logic and power supply) or LiYCY 7 x 1 mm <sup>2</sup> max 40 m (logic and power supply)	LiYCY 7 x 0,75 mm <sup>2</sup> max 20 m (logic and power supply) or LiYCY 7 x 1 mm <sup>2</sup> max 40 m (logic and power supply)
Conductor size	up to 1 mm <sup>2</sup> - available for 7 wires	up to 1 mm <sup>2</sup> - available for 7 wires
Connection type	to solder	to solder
Protection (EN 60529)	IP 67	IP 67

#### 17.2 Main connectors - 12 pin

CONNECTOR TYPE	POWER SUPPLY	POWER SUPPLY		
CODE	A2 ZM-12P	(A4) ZH-12P		
Туре	12pin female straight circular	12pin female straight circular		
Standard	DIN 43651	DIN 43651		
Material	Metallic	Plastic reinforced with fiber glass		
Cable gland	PG13,5	PG16		
Recommended cable	LiYCY 12 x 0,75 mm <sup>2</sup> max 20 m (logic and power supply)	LiYCY 10 x 0,14mm <sup>2</sup> max 40 m (logic) LiYY 3 x 1mm <sup>2</sup> max 40 m (power supply)		
Conductor size	0,5 mm <sup>2</sup> to 1,5 mm <sup>2</sup> - available for 12 wires	0,14 mm <sup>2</sup> to 0,5 mm <sup>2</sup> - available for 9 wires 0,5 mm <sup>2</sup> to 1,5 mm <sup>2</sup> - available for 3 wires		
Connection type	to crimp	to crimp		
Protection (EN 60529)	IP 67	IP 67		

#### 17.3 Fieldbus communication connectors

CONNECTOR TYPE	BC CAN	<b>open</b> (1)	BP PROFIBUS DP (1)		EH EtherCAT, EW POWERLINK, EI EtherNet/IP, EP PROFINET (2)	
CODE	C1 ZM-5PF	C2 ZM-5PM	C1 ZM-5PF/BP	C2 ZM-5PM/BP	C1 C2	ZM-4PM/E
Turne	5 pin female	5 pin male	5 pin female	5 pin male	4 pin male	
Туре	straight circular	straight circular	straight circular	straight circular		straight circular
Standard	M12 coding A –	2 coding A – IEC 61076-2-101 M12 coding B –		IEC 61076-2-101	M12 co	ding D – IEC 61076-2-101
Material	Me	tallic	Me	tallic		Metallic
Cable gland	Pressure nut - cab	le diameter 6÷8 mm	Pressure nut - cable diameter 6÷8 mm		Pressure nut - cable diameter 4÷8 mm	
Cable	CANbus Stand	lard (DR 303-1)	PROFIBUS DP Standard		Ethernet standard CAT-5	
Connection type	screw	terminal	screw terminal		terminal block	
Protection (EN 60529)	IF	267	IP 67		IP 67	

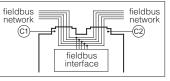
(1) E-TRM-\*\* terminators can be ordered separately - see tech table GS500

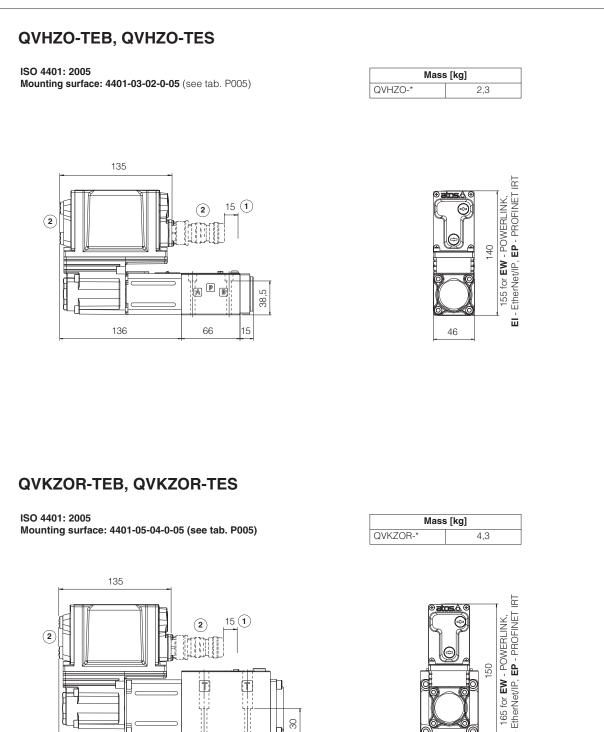
(2) Internally terminated

# 18 FASTENING BOLTS AND SEALS

	QVHZO	QVKZOR		
	<b>Fastening bolts:</b> 4 socket head screws M5x50 class 12.9 Tightening torque = 8 Nm	<b>Fastening bolts:</b> 4 socket head screws M6x40 class 12.9 Tightening torque = 15 Nm		
0	<b>Seals:</b> 4 OR 108; Diameter of ports A, B, P, T: Ø 7,5 mm (max)	Seals: 5 OR 2050; Diameter of ports A, B, P, T: Ø 11,2 mm (max)		

# BC and BP pass-through connection





Mass: 4,3 kg

(1) = Space to remove the connectors

(2) = The dimensions of all connectors must be considered, see section 15.4 and 15.5

#### 20 RELATED DOCUMENTATION

FS001	Basics for digital electrohydraulics	K800	Electric and electronic connectors
FS900	Operating and maintenance information for proportional valves	P005	Mounting surfaces for electrohydraulic valves
GS500	Programming tools	QB300	Quickstart for TEB valves commissioning
GS510	Fieldbus	QF300	Quickstart for TES valves commissioning

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